CSE 574: Class project

- Opportunistic Re-planning Agent
  Anupam Khulbe
Objectives

- Opportunistic – Agent should be able to take advantage of plan at hand for achieving new goals
- Conservative – Agent should not give up its current goal in order to achieve a new one
- Minimize re-planning / making local changes to the plan
Splitting goals into phases

- Breaking the goal into phases facilitates better merging of new goal into a plan
- Each phase can be accommodated into the plan at a point nearest to it (in terms of action costs)
  E.g. Delivering packages
- How to split the goal into phases?
Domain dimensions

- Logistics domain
  Dimension 1 – agent's location
  Dimension 2 – package's state

- Actions move and pickup/drop transition the state in 2 dimensions

- Goal in this domain split into two phases: picking up, and delivering the package
Goal epochs

- Agent's way of remembering important event along a plan trajectory (analogous to epoch in temporal planning)

- Plan trajectory is demarcated with event's relevant to each goal

- These act as points of re-entry into the plan after digressing to achieve a new goal (rather, a phase of it)
Approach

- Mark original plan trajectory with event (epochs) for the current goal set
- Split any newly assigned goal $g'$ into phases
- Use the planner for digressing and reentering the original plan for each phase
  - Abandon the goal, if cost incurred in any of the phases outweighs the goal utility, or if it invalidates any part of the original plan
Interesting questions...

- How to split the goals into right phases in a domain-independent way?

- How beneficial/difficult would it be to generate this epoch information during planning, as opposed to by post-processing the plan?

- How to do the same for durative actions and deadline goals?